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# Transient rheology of the uppermost mantle beneath the Mojave Desert, California

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## Abstract

Geodetic data indicate that the M7.1 Hector Mine, California, earthquake was followed by a brief period (a few weeks) of rapid deformation preceding a prolonged phase of slower deformation. We find that the signal contained in continuous and campaign global positioning system data for 2.5 years after the earthquake may be explained with a transient rheology. Quantitative modeling of these data with allowance for transient (linear biviscous) rheology in the lower crust and upper mantle demonstrates that transient rheology in the upper mantle is dominant, its material properties being typified by two characteristic relaxation times  $\sim 0.07$  and  $\sim 2$  years. The inferred mantle rheology is a Jeffreys solid in which the transient and steady-state shear moduli are equal. Consideration of a simpler viscoelastic model with a linear univiscous rheology (2 fewer parameters than a biviscous model) shows that it consistently underpredicts the amplitude of the first  $\sim 3$  months signal, and allowance for a biviscous rheology is significant at the 99.0% confidence level. Another alternative model – deep postseismic afterslip beneath the coseismic rupture – predicts a vertical velocity pattern opposite to the observed pattern at all time periods considered. Despite its plausibility, the advocated biviscous rheology model is non-unique and should be regarded as a viable alternative to the non-linear mantle rheology model for governing postseismic flow beneath the Mojave Desert.

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*Keywords:* postseismic relaxation; viscoelasticity; mantle; rheology; global positioning system

## 1. Introduction

The rheology of the lithosphere and asthenosphere is of central importance for understanding the evolution of plate boundary zones, the role of crust–mantle coupling in driving continental deformation, and predicting the response of the litho-

osphere to glacial and lacustrine loads as well as earthquakes. In turn, the study of this response is the principal way in which the rheology of the deep subsurface is inferred.

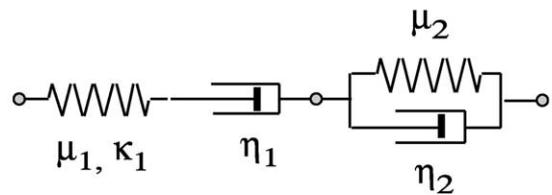
The rheology of the bulk Earth is generally represented in terms of the depth-dependent distribution of its viscoelastic structure [1]. At time-scales of  $\sim 10^6$  years this is based on the correlation of the long wavelength geoid with Earth's interior convective flow pattern constrained by the surface kinematics (e.g. [2,3]). Generation of surface and subsurface topography over geologic

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time also provides a window into the flow of the lower crust and uppermost mantle, yielding estimates of the viscosities of these regions [4]. At timescales of several thousand years and wavelengths of hundreds to thousands of km, most constraints on rheology are provided by postglacial rebound data. (e.g. summaries by [1] and [5]), yielding estimates of the elastic plate thickness and upper and lower mantle viscosity structure. At timescales of several months to several decades and wavelengths of  $< 1000$  km, geodetic observations of postseismic relaxation following major (magnitude  $\sim > 7$ ) earthquakes (e.g. [6–14]) allow estimation of elastic plate thickness and lower crust and upper mantle viscosities.

The focus of this paper is the viscoelastic structure of the lower crust and uppermost mantle. Postseismic crustal deformation measurements provide the greatest wealth of data bearing on the rheology of these regions. Experience has shown that such data are often difficult to interpret unambiguously owing to the similar ground deformation predicted by different postseismic flow mechanisms, notably afterslip and bulk viscoelastic relaxation [15–19]. When viscoelastic mechanisms can be satisfactorily discriminated from other candidate processes, one further needs to reckon with the constitutive relation between stress and strain since it is fundamental in controlling the viscoelastic response of the lower crust and mantle. The rheology of these regions is almost certainly more complicated than that of a simple Maxwell viscoelastic solid which is usually adopted in deformation modeling studies. Rocks in the laboratory generally exhibit a non-linear response to stress over a broad range of frequencies [20,21]. At seismic frequencies, attenuation phenomena are well explained with an absorption band model [21] involving relaxation over a continuum of frequencies ranging from about 0.001 to 10 Hz. This behavior may be roughly approximated as that of a homogeneous standard linear solid Earth of viscosity  $\sim 10^{16}$  Pa s [22]. This is well below the value of  $\sim 10^{19}$  Pa s deduced in most postseismic relaxation studies, but almost all of these studies have assumed a Maxwell rheology. It has been previously remarked [22] that postglacial rebound takes place on a timescale



**Maxwell element**      **Kelvin element**

Fig. 1. A Burgers body rheology consists of a Maxwell element in series with Kelvin element, or equivalently a dashpot in series with a Zener standard linear solid. The quantities  $\eta_1$  and  $\{\mu_1, \kappa_1\}$  are the steady-state viscosity and {shear, bulk} modulus, respectively, and  $\eta_2$  and  $\mu_2$  are the transient viscosity and shear modulus, respectively.

that is sensitive to both anelastic and viscous deformation mechanisms in the Earth. The question arises as to whether the mechanisms that control both seismic wave attenuation and long term viscous deformation also play a role in postseismic deformation and, if so, whether postseismic deformation observations can capture the transition between the two deformation modes.

At the small strains and timescales involved in seismic wave attenuation and postseismic relaxation, a transient response is expected [21]. Recent studies which focus on the earliest postseismic response yield effective viscosities of order  $10^{17}$  Pa s [15,23], and an explanation involving a transient rheology comes to the forefront. The large strain rates observed in the epicentral region of the 1992 Landers earthquake during the first three months postseismic period [16], in contrast with the post-three month period, have been interpreted by Ivis [23] as the response of heterogeneous lower crust which, in terms of composite media theory, is best described as a transient rheology represented by a Burgers body. Further evidence suggestive of a transient rheology is provided by postseismic deformation observed by global positioning system (GPS) and InSAR in the 9 months after the M7.1 1999 Hector Mine earthquake (Fig. 2). Pollitz et al. [15] inferred a relaxing mantle source of the postseismic deformation and proposed that the effective mantle viscosity increased with time from  $\sim 5 \times 10^{17}$  Pa s in the first few months to  $\sim 2 \times 10^{19}$  Pa s between 3 months and 3 years after the respective earthquakes.

Such a trend with time can plausibly arise with either a non-linear [15,24] or a transient rheology.

In this paper we consider in greater detail the implications of post-Hector Mine deformation measurements and address whether or not these measurements can be explained with a transient rheology. It is likely possible, in principle, to interpret available postseismic deformation data in terms of a transient rheology that merges the behavior of the absorption model at short timescale and viscous behavior at long timescale (i.e. [22]). Here we seek an interpretation of these data with the simplest realization of a transient rheology – a Burghers body (Fig. 1). For shear deformation, the constitutive equation governing a Burghers body is [25]:

$$2\eta_2\ddot{\epsilon} + 2\mu_2\dot{\epsilon} = \frac{\eta_2}{\mu_1}\ddot{\sigma} + \left[1 + \frac{\mu_2}{\mu_1} + \frac{\eta_2}{\eta_1}\right]\dot{\sigma} + \frac{\mu_2}{\eta_1}\sigma \quad (1)$$

where  $\eta_1$ ,  $\mu_1$  are steady-state viscosity and shear modulus, respectively, and  $\eta_2$ ,  $\mu_2$  are the transient viscosity and transient shear modulus, respectively (Fig. 1). For a constant stress load  $\sigma_0$ , the strain response is given by:

$$\epsilon = \frac{\sigma_0}{2\mu_1} + \frac{\sigma_0}{2\mu_2}[1 - \exp(-t/\tau_2)] + \frac{\sigma_0}{2\mu_1} \frac{t}{\tau_1} \quad (2)$$

where  $\tau_1 = \eta_1/\mu_1$  and  $\tau_2 = \eta_2/\mu_2$ . The response to an imposed constant stress step is thus a superposition of three effects: the instantaneous elastic response, an exponentially-decaying transient response, and a linearly-increasing steady-state response. The transient and steady-state responses are associated with relaxation times  $\tau_2$  and  $\tau_1$ , respectively. If  $\tau_2 \ll \tau_1$ , then the transient response will be relatively rapid and distinguishable from the steady-state response. If existing postseismic observations are interpreted with this material, then the rapid early response is associated with the short ‘transient’ characteristic relaxation time of the Kelvin element of the solid –  $\tau_2$ , whereas the slower later response is controlled by the longer ‘steady’ characteristic relaxation time of the Maxwell element of solid –  $\tau_1$  (Fig. 1).

We shall make use of three-component GPS data covering the period from 10 days to 2.5 years after the Hector Mine earthquake. This samples both the very early, rapid and later, relatively

slow postseismic deformation phases. Although earlier observations are available, we do not make use of deformation data from the first 10 days postseismic period in order to avoid the possible influence of aftershocks [26]. We find that the GPS time series contain signals sensitive to both crust and mantle relaxation, and in the framework of linear viscoelasticity theory, they are most consistent with a transient rheology of the mantle characterized by two distinct relaxation times.

## 2. Postseismic GPS observations

We employ three-component continuous GPS data provided by the southern California Integrated GPS Network (SCIGN) [27] and campaign GPS data provided by the US Geological Survey (USGS) [28]. The locations of these sites are shown in Fig. 2. Sixteen of the 29 sites are SCIGN sites; 13 sites are USGS campaign sites with varying levels of campaign sampling. There are a total of 47 526 time samples from 135 time series employed in this analysis.

The time series for the SCIGN sites have been processed in network mode using GAMIT/GLOBK software in a fixed North America refer-

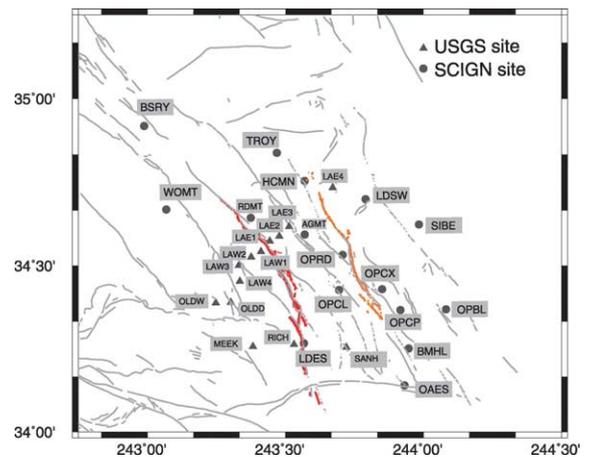
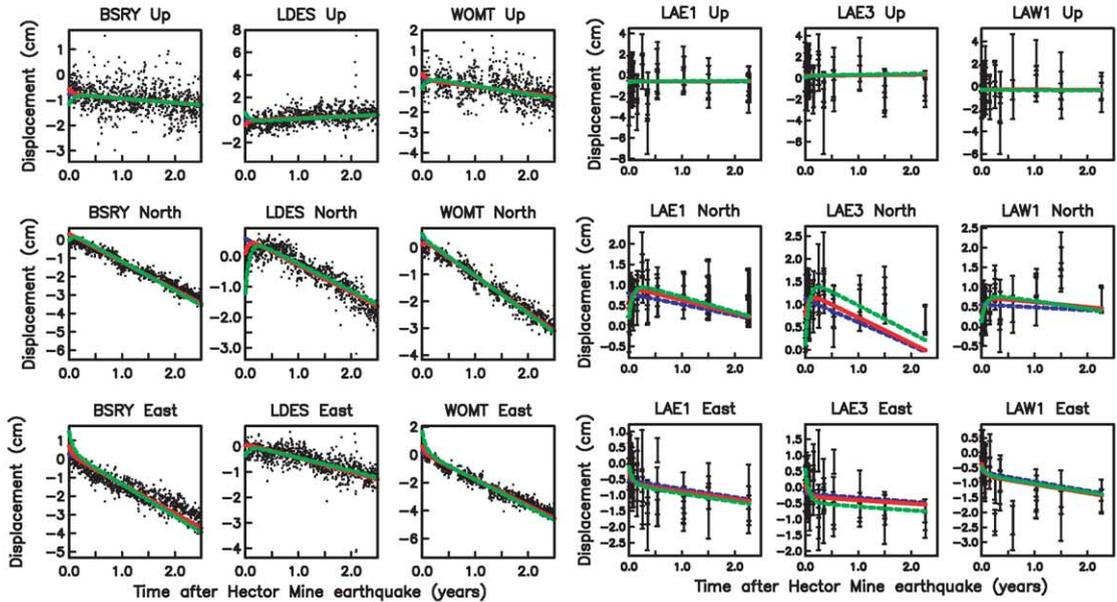


Fig. 2. Locations of 29 GPS sites used in this study. Sixteen of them are part of the SCIGN continuous GPS network; 13 are USGS campaign GPS sites. Red and orange lines denote surface traces of the 1999 Hector Mine and 1992 Landers earthquakes, respectively.

A (SCIGN time series)

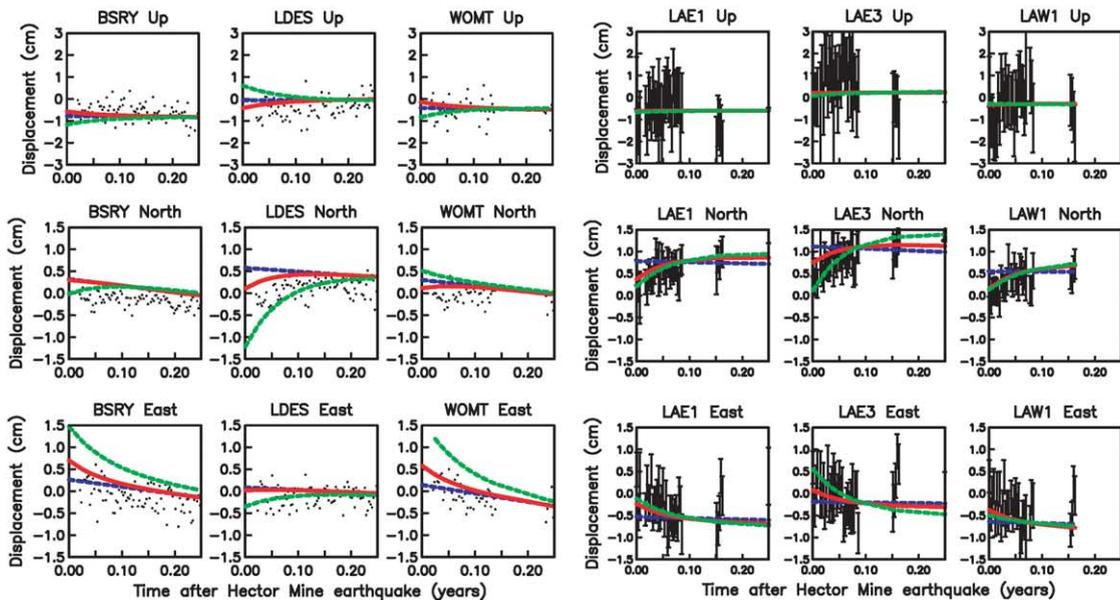
B (USGS time series)



— Biviscous mantle  
- - - Univiscous rheology  
- - - Biviscous lower crust

C (SCIGN time series)

D (USGS time series)



ence frame defined by four IGS fiducial sites tightly constrained to ITRF96, then rotated to a regional reference frame designed to match a known set of 30 SCIGN station coordinates and velocities in southern California [29]. The time series for the 13 USGS sites have been augmented by a subset of SCIGN data for the other 16 sites at times corresponding to the observation times of the campaign sites. The 29 collective sites were then processed in network mode using GYPSY software in a fixed North America reference frame defined by 13 ITRF97 fiducial stations [30]. This allows estimation of velocities at the 13 USGS campaign sites in a reference frame that is easily related to the reference frame of the SCIGN network processing. The difference between the two reference frames is well described as the difference between two velocity shift vectors, obtained for each network separately as described in Section 3.1.

The vertical time series are particularly susceptible to annual and semi-annual variations likely arising from seasonal pressure fluctuations [31]. In order to remove this signal, I estimate four sinusoidal components (equivalent to the amplitude and phase of the annual and semi-annual signals) simultaneously with velocity and initial position, then subtract the determined sinusoidal components from the vertical time series. Typical amplitude of the annual and semi-annual terms are about 1–2 mm.

One of the sites, OAES (Fig. 2) is found to exhibit a sharp acceleration in motion towards the south about 2 years after the Hector Mine earthquake in the SCIGN data time series. We attribute this to local deformation sources unrelated to postseismic relaxation from the Hector Mine earthquake. For this reason we exclude data from this site in our evaluation of candidate viscoelastic models.

Time series are shown in Fig. 3a for three selected SCIGN sites and in Fig. 3b for three selected USGS sites for the first 2.5 years; Fig. 3c,d show the same time series for the first 0.25 years. A pronounced curvature with time is apparent, suggesting that more than one time signal (i.e. a superposition of a steady-state signal and exponentially-decaying signals) is present. These time series reveal that the first  $\sim 0.2$ -yr postseismic period is generally associated with much faster deformation rates than at later times. The chief characteristics of this ‘transient relaxation’ period are its rapidity and its ubiquitous presence throughout the considered networks, suggesting a common underlying broadscale physical process. In general, the SCIGN network observations provide the densely sampled time-dependent signals critical to detecting both potential transient and steady-state signals. The observations provided by the USGS network are less dense in time but more dense in space, especially helping cover the area near the 1992 Landers rupture. With both data sets the use of vertical in addition to horizontal components provides vital information on the relative contributions of crust and mantle relaxation.

### 3. Modeling of postseismic deformation

#### 3.1. Representation of postseismic deformation

Following Pollitz et al. [15], we interpret the GPS time series as a superposition of two distinct processes: (1) steady tectonic loading, and (2) viscoelastic relaxation of the lower crust and upper mantle. We model 3-D displacement  $\mathbf{u}(\hat{\mathbf{r}}_i, t)$  at GPS site  $\hat{\mathbf{r}}_i$  at Earth’s surface and time  $t$  after the earthquake as:

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←  
 Fig. 3. (A) Three-component GPS time series for the first 2.5 years following the Hector Mine earthquake at three selected sites as recorded by the SCIGN continuous stations. Red curves are the predicted displacements (e.g.  $\mathbf{u}(\hat{\mathbf{r}}_i, t)$ ) as prescribed by Eq. 3 based on the preferred transient rheology model (explained in Section 4). Dashed green curves are the predicted displacements on a transient lower crust rheology model (Section 5). Dashed blue curves are the predicted displacements on a univiscous rheology model (Section 4). (B) GPS time series at three selected sites as recorded by the USGS campaign measurements, with standard errors. (C) and (D) are a close-up view of the same time series shown in (A) and (B) for the first 0.25 years.

$$\mathbf{u}(\hat{\mathbf{r}}_i, t) = \mathbf{u}_{\text{def}}(\hat{\mathbf{r}}_i, t) + \mathbf{v}_{\text{load}}(\hat{\mathbf{r}}_i)t + \mathbf{a}_i + \mathbf{b}t \quad (3)$$

where  $\mathbf{u}_{\text{def}}$  and  $\mathbf{v}_{\text{load}}$  are the contributions of viscoelastic relaxation and steady tectonic loading, respectively, the  $\{\mathbf{a}_i\}$  are constant station vector offsets, and  $\mathbf{b}$  is a common mode velocity shift of the regional reference frame employed in the GPS analysis with respect to the epicentral region of the earthquake. Since  $\mathbf{u}_{\text{def}}(\hat{\mathbf{r}}_i, t) = 0$  at  $t = 0$ , the  $\{\mathbf{a}_i\}$  would be zero given perfect observations. However, given the fact that observations are imperfect and, especially, that many time series in the data sets begin much later than the immediate postseismic period (several SCIGN sites used in the present study were emplaced  $> 2$  months after the earthquake), it is necessary to introduce these station offsets.

In practice, both  $\mathbf{a}_i$  and  $\mathbf{b}$  for a given deformation component  $\mathbf{u}_{\text{def}}$  are determined separately for each GPS network (SCIGN and USGS) by fitting the theoretical displacement  $\mathbf{u}(\hat{\mathbf{r}}_i, t)$  to the observed time series  $\mathbf{u}_{\text{obs}}(\hat{\mathbf{r}}_i, t_{ij})$ , where  $t_{ij}$  are the available observation times at site  $i$ . Specifically we minimize the following misfit functions for the three Cartesian indices  $k = 1, 2, 3$ :

$$\chi_k^2 = \sum_i \sum_j \frac{[\hat{\mathbf{x}}_k(\hat{\mathbf{r}}_i) \cdot \mathbf{u}(\hat{\mathbf{r}}_i, t_{ij}) - \hat{\mathbf{x}}_k(\hat{\mathbf{r}}_i) \cdot \mathbf{u}_{\text{obs}}(\hat{\mathbf{r}}_i, t_{ij})]^2}{[\sigma_{ijk}]^2} \quad (4)$$

where  $\hat{\mathbf{x}}_k(\hat{\mathbf{r}}_i)$  is the local unit vector at  $\hat{\mathbf{r}}_i$  on the spherical Earth pointing in the due East ( $k = 1$ ), North ( $k = 2$ ), and up ( $k = 3$ ) directions, respectively, and  $\sigma_{ijk}$  is the standard deviation (SD) of the  $k$ -direction measurement at site  $i$  and time  $t_{ij}$ . Thus, given sets of time series from two station networks, we minimize six misfit functions in order to obtain two sets  $\{\mathbf{a}_i, \mathbf{b}\}$ , one set for each network. This involves three inversions for 17 parameters (16  $\hat{\mathbf{x}}_k \cdot \mathbf{a}_i$  and  $\hat{\mathbf{x}}_k \cdot \mathbf{b}$ ) using SCIGN data and three inversions for 30 parameters (29  $\hat{\mathbf{x}}_k \cdot \mathbf{a}_i$  and  $\hat{\mathbf{x}}_k \cdot \mathbf{b}$ ) using USGS data. We assume no steady-state component for the vertical data, so that  $\hat{\mathbf{x}}_3 \cdot \mathbf{b} = 0$  a-priori. A total of  $51 + 90 - 2 = 139$  parameters are estimated in this fashion. After propagation of the data errors typical values of  $\mathbf{a}_i$  are  $\sim \pm 5$  mm with standard errors  $\sim 0.1$ – $0.3$  mm. The reference frame shift between the two data sets determined by their respective  $\mathbf{b}$ -values is  $(13.6 \pm 0.17 \text{ mm/yr}, 11.8 \pm 0.14 \text{ mm/yr})$  in (East,

North) coordinates. Removal of this common mode shift between the SCIGN and USGS networks renders them consistent at the sub-mm/yr level.

The background tectonic loading component  $\mathbf{v}_{\text{load}}(\hat{\mathbf{r}}_i)$  is prescribed by a uniform engineering strain rate rate of  $0.1 \mu\text{rad/yr}$  resolved onto a  $\text{N}40^\circ\text{W}$  trending vertical plane. This value is obtained from several trilateration surveys in the central Mojave Desert prior to 1992 [32], and it is considered a good representation of the pre-Landers velocity field.

The viscoelastic deformation component  $\mathbf{v}_{\text{def}}$  depends on the viscoelastic structure and the source models of the major contributing earthquakes – the 1992 Landers and 1999 Hector Mine earthquakes. We adopt the slip model of [33] for the Landers earthquake and [34] for the Hector Mine earthquake. The viscoelastic structure is parameterized in terms of depth-dependent elastic moduli (bulk and shear modulus) and viscosities in the ductile lower crust and mantle (Fig. 4). The lower crust in the viscoelastic model is bounded by the maximum depth extent of regional earthquakes [35] and the Moho depth [36]. For simplicity we assume that both the lower crust and upper mantle are homogeneous.

### 3.2. Choice of rheology

Many possibilities exist for lower crust and upper mantle viscosity structure that could explain the primary patterns in the GPS observations. For example, if we were to allow both the lower crust and mantle to be a Burghers solid, then in addition to known steady-state elastic parameters in these regions we would need to reckon with six additional unknowns – the transient viscosity, transient shear modulus, and steady-state viscosity in both of these regions. In order to limit the range we restrict the possibility of transient rheology to one layer only, i.e. either the lower crust or upper mantle is permitted to have a Burghers body rheology, but the other is assumed Maxwell viscoelastic.

The behavior of a Burghers body (Fig. 1) may be represented by its Laplace-transformed shear modulus, which may be derived from Eq. 1:

## Postseismic Deformation: Candidate Models

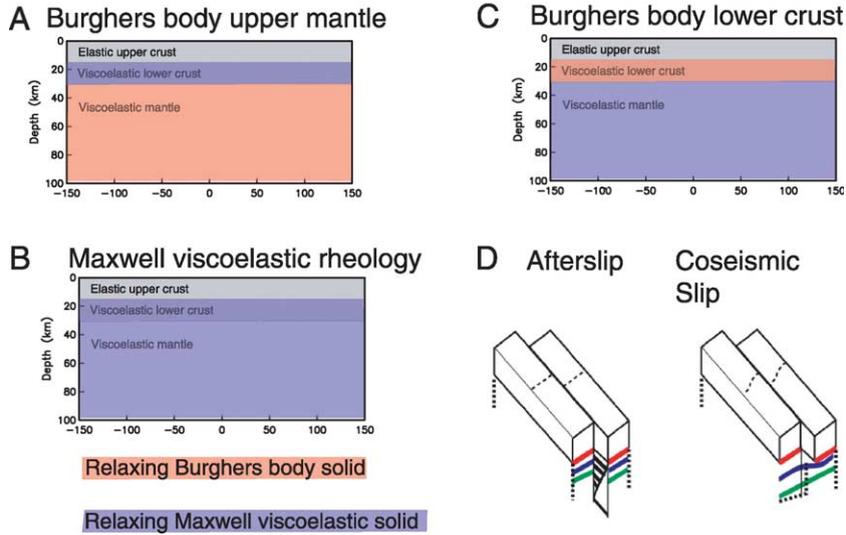


Fig. 4. Four different candidate models for postseismic deformation considered in this study. (A), (B), and (C) are viscoelastic models with various combinations of Burgers body and Maxwell rheologies in the lower crust and upper mantle. Case (C) is referred to as ‘univiscous rheology’ in the text. The afterslip model in (D) is shown schematically as discontinuous slip in the deeper extension of the coseismic slip region.

$$\mu(s) = \mu_1 s \frac{(s + \tau_2^{-1})}{(s + \tau_2^{-1})(s + \tau_1^{-1}) + \frac{\mu_1 s}{\eta_2}} \quad (5)$$

Noteworthy properties of  $\mu(s)$  are that in the limit  $\eta_2 \rightarrow \infty$ , the material behaves as a Maxwell viscoelastic solid. In the limit  $\eta_1 \rightarrow \infty$ , the material behaves as a standard linear solid with transformed shear modulus:

$$\mu(s) = \frac{\mu_1 s + \mu' \tau^{-1}}{s + \tau^{-1}} \quad (6)$$

$$\mu' = \frac{\mu_1 \mu_2}{\mu_1 + \mu_2} \quad (7)$$

$$\tau = \frac{\eta_2}{\mu_1 + \mu_2} \quad (8)$$

The quantity  $\mu'$  is the effective shear modulus of the material in the limit of complete relaxation, i.e. the material does not relax to a state of zero stress but retains a finite strength at large times. Since  $\eta_1$  is not arbitrarily large, Eq. 5 demands that at sufficiently large time the material will completely relax to a state of zero stress, but if  $\eta_1 \gg \eta_2$ , then at times that are large compared

with  $\tau_2$  but smaller than  $\tau_1$ , the material will relax to a finite strength  $\mu'$ .

We shall consider four physical models of postseismic deformation (Fig. 4). Three of these are viscoelastic models, and the fourth is an afterslip model. In Section 4.1 we focus on the model characterized by a transient rheology in the upper mantle and a Maxwell rheology in the lower crust (Fig. 4a), comparing its performance with that of a univiscous rheology (Fig. 4b). The remaining viscoelastic model specifies a transient rheology in the lower crust (Fig. 4c) and is discussed in Section 4.2. The afterslip model (Fig. 4d) will be discussed in Section 5.

### 4. Determination of rheology parameters

#### 4.1. Biviscous mantle model

The viscoelastic relaxation component  $\mathbf{u}_{\text{def}}(\hat{\mathbf{r}}, t)$  is calculated according to the method of [37]. This method yields the postseismic deformation at arbitrary points and times on a spherically stratified

viscoelastic medium for given dislocation sources. One advantage of the method is that it is designed to accommodate a linear rheology directly in terms of the Laplace-transformed shear modulus, and as such the shear modulus prescribed by Eq. 5 may be directly implemented.

Eq. 4 provides a measure of model misfit with respect to the time series observations. Although this measure allows identification of best-performing models, it does not illuminate the sensitivity of specific portions of the time series to the various model parameters. For model evaluation we therefore prefer the alternative of comparing modeled and observed velocities in specific time intervals  $(t_1, t_2)$ . Model velocity at site  $i$  is:

$$\mathbf{v}(\hat{\mathbf{r}}_i; t_1, t_2) = \frac{\mathbf{u}(\hat{\mathbf{r}}_i, t_2) - \mathbf{u}(\hat{\mathbf{r}}_i, t_1)}{t_2 - t_1} \quad (9)$$

For each of the three Cartesian indices  $k = 1, 2, 3$  observed velocity  $\hat{\mathbf{x}}_k(\hat{\mathbf{r}}_i) \cdot \mathbf{v}_{\text{obs}}(\hat{\mathbf{r}}_i; t_1, t_2)$  with corresponding SD  $\sigma_{ik}(t_1, t_2)$  is derived from the observed time series by determining the best-fitting straight line fit to the  $\hat{\mathbf{x}}_k(\hat{\mathbf{r}}_i) \cdot \mathbf{v}_{\text{obs}}(\hat{\mathbf{r}}_i, t)$  within  $(t_1, t_2)$  and propagation of the data errors. Our measure then becomes the time-dependent velocity misfit functions

$$\chi_k^2(t_1, t_2) = \sum_i \frac{[\hat{\mathbf{x}}_k(\hat{\mathbf{r}}_i) \cdot \mathbf{v}(\hat{\mathbf{r}}_i; t_1, t_2) - \hat{\mathbf{x}}_k(\hat{\mathbf{r}}_i) \cdot \mathbf{v}_{\text{obs}}(\hat{\mathbf{r}}_i; t_1, t_2)]^2}{[\sigma_{ik}(t_1, t_2)]^2} \quad (10)$$

The summation over  $i$  is over the combined SCIGN and USGS data sets.

Fig. 5a summarizes the rheologies chosen for the upper crust (purely elastic), lower crust (Maxwell viscoelastic), and upper mantle (Burghers body). Among the five parameters that control the complete rheology, only the steady-state shear and bulk moduli  $\{\mu_1, \kappa_1\}$  are known with reasonable certainty. Noting Eq. 7, we consider two values of  $\mu'$ :  $\mu' = 0.5 \times \mu_1$  (50% relaxation during transient phase) and  $\mu' = 0.75 \times \mu_1$  (25% relaxation during transient phase). It is necessary to choose a relevant range of  $\gamma$ , defined as the ratio of steady-state viscosity between the crust and mantle. Although previous work [15] suggests a large ratio in effective viscosity, this is not directly related to steady-state viscosity. We consider three

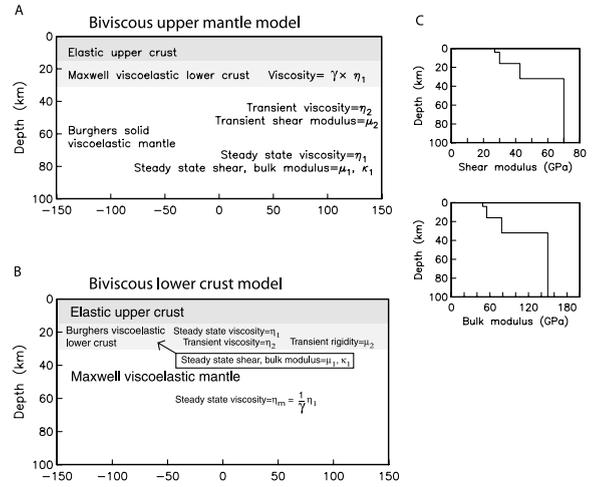


Fig. 5. (A) Parameterization of a biviscous upper mantle model. Each of the upper crust, lower crust, and upper mantle is taken to have uniform material properties. The ratio of crust-to-mantle viscosity is denoted by  $\gamma$ . The lower crust and upper mantle are assumed to behave as a Maxwell viscoelastic solid and Burghers body, respectively. Five parameters are needed to describe the mantle rheology. The steady-state shear and bulk moduli  $\mu_1$  and  $\kappa_1$  are given in (c). The transient shear modulus  $\mu_2$  is constrained by the choice of  $\mu'$ , which prescribes  $\mu_2$  through Eq. 7. The remaining parameters  $\eta_1$  (steady-state viscosity) and  $\eta_2$  (transient viscosity) are variable. (B) Parameterization of a biviscous lower crust model. The lower crust and upper mantle are assumed to behave as a Burghers body and Maxwell viscoelastic solid, respectively. The ratio of crust-to-mantle viscosity is denoted by  $\gamma$ . (C) Shear modulus  $\mu_1$  and bulk modulus as a function of depth as constrained by seismic information [36].

possible values for this ratio:  $\gamma = 1, 7$ , and  $20$ . The remaining unknown parameters are then  $\eta_2$  and  $\eta_1$  – the transient and steady-state viscosities of the mantle.

We perform a grid search for  $\eta_2$  and  $\eta_1$  based on fitting all 135 time series with a model of post-seismic relaxation and evaluating misfit with Eq. 10 for each model using three time intervals  $(t_1, t_2) = (10 \text{ days}, 3 \text{ months}), (10 \text{ days}, 9 \text{ months}),$  and  $(3 \text{ months}, 2.5 \text{ years})$ . The results are shown in Fig. 6. Among the values of  $\gamma$  considered, only values  $\gamma \geq 7$  provide a satisfactory fit to the vertical velocity field during the later time period. Although only slightly better fits to the complete dataset are achieved with  $\gamma = 7$  compared with  $\gamma = 20$ , for concreteness we choose the value  $\gamma = 7$  for further consideration. Examining Fig. 6c,d,

between the two values of  $\mu'$  considered, the fits over the later (3 months to 2.5 year) time period are similar, but over the earlier time periods the smaller value  $\mu' = 0.5 \times \mu_1$  provides a vastly better fit to the data. In this case (Fig. 6c), the misfit patterns for the later time period have minimum misfit at roughly constant  $\eta_1$  with little sensitivity to  $\eta_2$ . In contrast, the minimum misfit domain for the early time period defines roughly a line of slope  $-1$  in  $\log \eta_2 / \eta_1 - \log \eta_1$  space, or simply  $\eta_2 \sim \text{constant}$ . The intersection of these two domains yields a model prescribed by values  $\mu' = 0.5 \times \mu_1$  (equivalent to  $\mu_2 = \mu_1$ , i.e. a Jeffreys solid),  $\gamma = 7$ ,  $\eta_1 = 4.6 \times 10^{18}$  Pa s, and  $\eta_2 = 0.35 \times \eta_1 = 1.6 \times 10^{17}$  Pa s. This model is henceforth considered the preferred model in the remainder of this paper. The velocity and displacement fields derived from this model are consistent with essentially all data sets considered, but we note that only slightly worse fits are obtained by a model with similar  $\mu'$  and  $\eta_1$  but somewhat higher transient viscosity  $\eta_2 \sim 0.1 \times \eta_1 \sim 5 \times 10^{17}$  Pa s. However,  $\eta_2$  less than about  $10^{17}$  Pa s or greater than about  $5 \times 10^{17}$  Pa s is inconsistent with the observations.

We compare the performance of the preferred biviscous model with the equivalent univiscous model ( $\eta_2 = \infty$ , i.e. Maxwell viscoelastic), other factors being equal. A grid search for  $\eta_1$  yields minimum misfit at  $\eta_1 = 4.6 \times 10^{18}$  Pa s. Table 1 lists the misfit values of the best biviscous and univiscous models and the number of time series with useful velocity estimates. Application of an F-test [38] to the early-period horizontal data alone shows that the biviscous model (variable,  $\mu'$ ,  $\eta_1$ ,  $\eta_2$ ) is a significant improvement to the

univiscous model (variable  $\eta_1$ ) at the 99.0% confidence level. The principal shortcoming of the univiscous model is that, since its material relaxation time is  $\sim 2$  years, it generally does not capture the amplitude of the transient observed during the first 0.2 year (Fig. 3c,d). This is verified by comparison of observed and calculated horizontal velocities within the two considered time periods (Fig. 7). It shows that the biviscous model adequately accounts for the observed velocities at both early and later time periods. The univiscous model exhibits similarly good agreement during the later time period but systematic disagreement during the early time period when modeled velocities are generally smaller than observed.

#### 4.2. Biviscous lower crust model

The biviscous lower crust model is shown schematically in Fig. 4b and parameterized in Fig. 5b. We find that there is no model in this class which fits the horizontal and vertical data simultaneously. Illustrative examples are shown in Fig. 9 for various slices of model space. Each misfit curve has been scaled by the misfit achieved by the preferred biviscous mantle model. For the slice shown in Fig. 9a ( $\gamma = 7$ ,  $\mu' = 0.5 \times \mu_1$ , and  $\eta_2 / \eta_1 = 0.004$ ), three of the curves approach unity and thus fit the corresponding data set equally well as the biviscous mantle model, but the fourth and fifth, corresponding to uplift during the early postseismic time period (10 days to 3 months, 10 days to 9 months), do not. The model obtained where the three satisfactory curves approximately intersect has lower crust viscosities of  $\eta_1 \sim 1.9 \times 10^{19}$  Pa s and  $\eta_2 \sim 7.5 \times 10^{16}$  Pa s, and

Table 1  
Velocity-misfit of biviscous and univiscous models

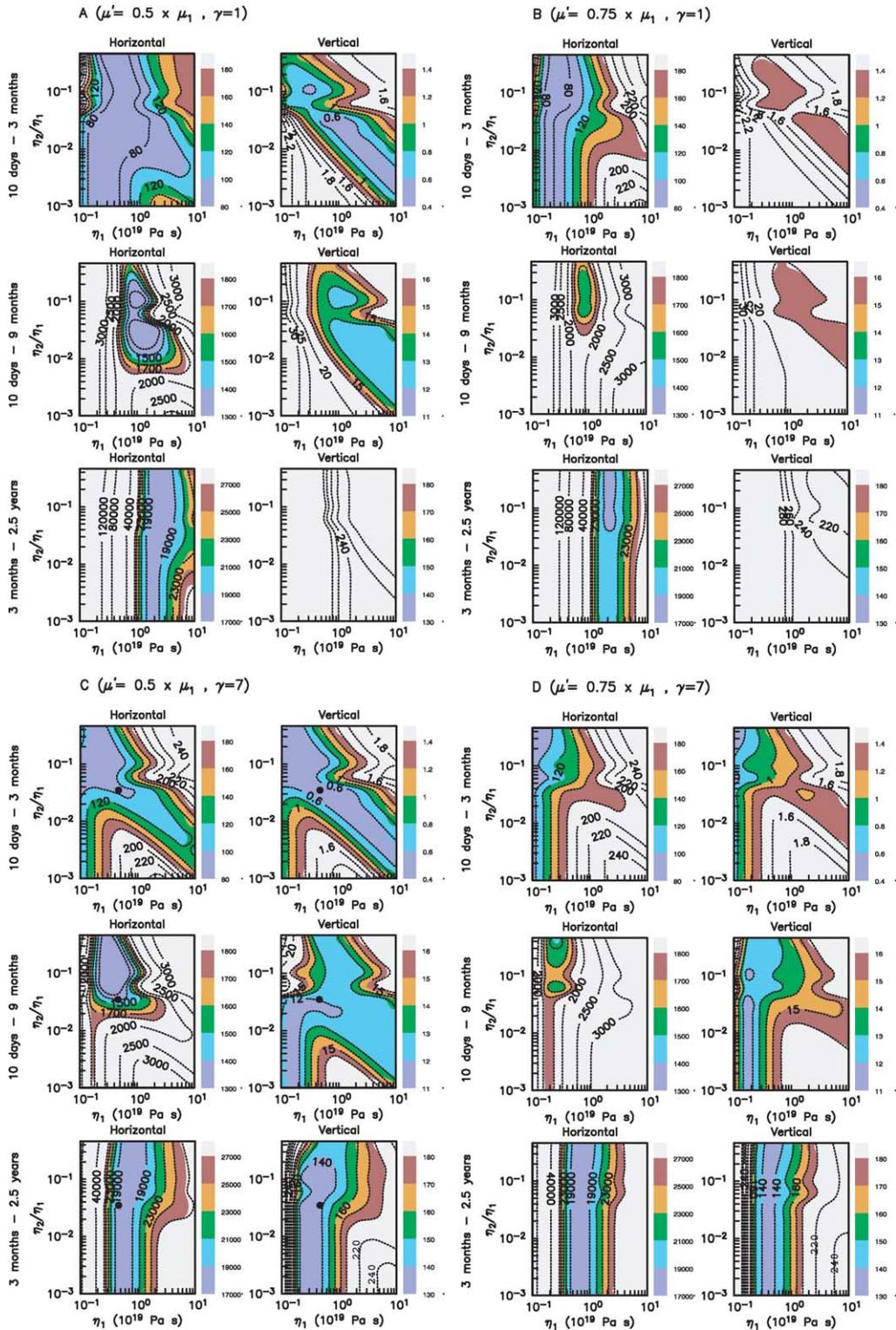
	10 days–3 months		10 days–9 months		3 months–2.5 years	
	horizontal	vertical	horizontal	vertical	horizontal	vertical
$\chi_{bi}^2$ <sup>a</sup>	112.6	0.48	1391	12.1	18508	145.4
$\chi_{umi}^2$ <sup>b</sup>	221.8	1.64	2428	15.2	18525	146.0
$N$	16	5	29	14	29	16

All misfits are computed with Eq. 10.

$N$  is the number of sites with useful velocity measurements.

<sup>a</sup>  $\chi_{bi}^2$  is the misfit computed on the preferred biviscous model ( $\mu' = 0.5 \times \mu_1$ ,  $\eta_1 = 4.6 \times 10^{18}$  Pa s,  $\eta_2 = 1.6 \times 10^{17}$  Pa s,  $\gamma = 7$ ).

<sup>b</sup>  $\chi_{umi}^2$  is the misfit computed on the best-fitting univiscous model ( $\eta_1 = 4.6 \times 10^{18}$  Pa s,  $\eta_2 = \infty$ ,  $\gamma = 7$ ).



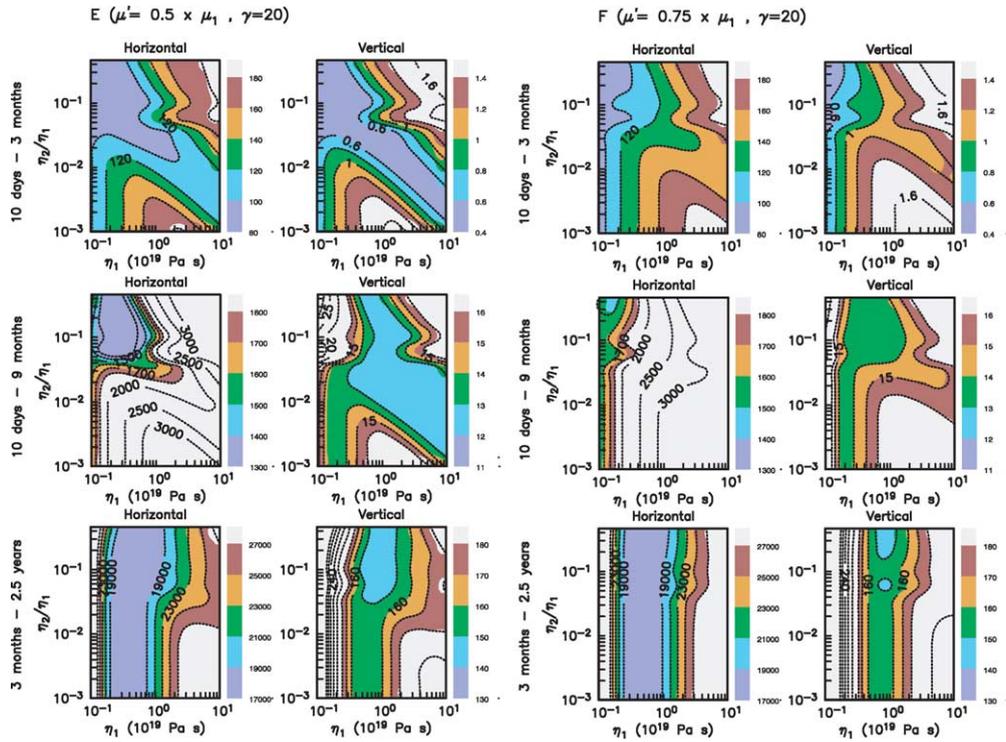


Fig. 6. Misfit  $\chi^2(t_1, t_2)$  of model velocity with respect to observed velocity as a function of  $\eta_1$  and the ratio  $\eta_2/\eta_1$  for (A,C,E)  $\mu' = 0.5 \times \mu_1$  and (B,D,F)  $\mu' = 0.75 \times \mu_1$ . Parts (A,B), (C,D), and (E,F) correspond to  $\gamma = 1, 7,$  and  $20$ , respectively. Referring to Eq. 10, horizontal misfit is the sum  $\chi_1^2 + \chi_2^2$ , and vertical misfit is  $\chi_3^2$ . Note that the minimum misfit domains obtained for the early (10 days to 3 months; 10 days to 9 months) and later (3 months to 2.5 years) time periods are compatible in (C) but incompatible in (D). Preferred biviscous model (Section 4) is indicated with filled black circle in the subplots of (C).

mantle viscosity  $\eta_m \sim 2.7 \times 10^{18}$  Pa s. The predictions of the uplift pattern for this model are shown in Fig. 8b where they may be compared with the predictions of the preferred biviscous mantle model (Fig. 8a). The patterns of calculated vertical response in the 3-month to 2.5-year period are similar for both the biviscous lower crust and biviscous mantle models, but the models diverge as the time period encompasses more of the earlier postseismic epoch, with the biviscous lower crust model performing progressively worse. Among other models in this class, increasing the ratio  $\eta_2/\eta_1$  (Fig. 9c,d) worsens the horizontal–vertical incompatibility; decreasing the ratio further produces behavior indistinguishable from the univiscous model. As was found for the class of biviscous mantle models, taking smaller  $\gamma$  (Fig. 9b,d) does not improve the fit of the vertical data for the early periods and clearly worsens

the fit of the vertical data for the later time period.

## 5. Discussion

The fits of the selected time series using the preferred biviscous mantle model are shown with the red solid curves in Fig. 3. The model fits the primary patterns exhibited by this data: early, rapid transient behavior for the first  $\sim 0.2$  years followed by deformation at slower rates for the succeeding 2.3 years. Most time series are well fit for both the early and late periods as well as the transition between transient and steady-state relaxation. This is also demonstrated by the overall agreement between predicted and observed horizontal velocity components (Fig. 7a).

The vertical GPS time series are also fit fairly

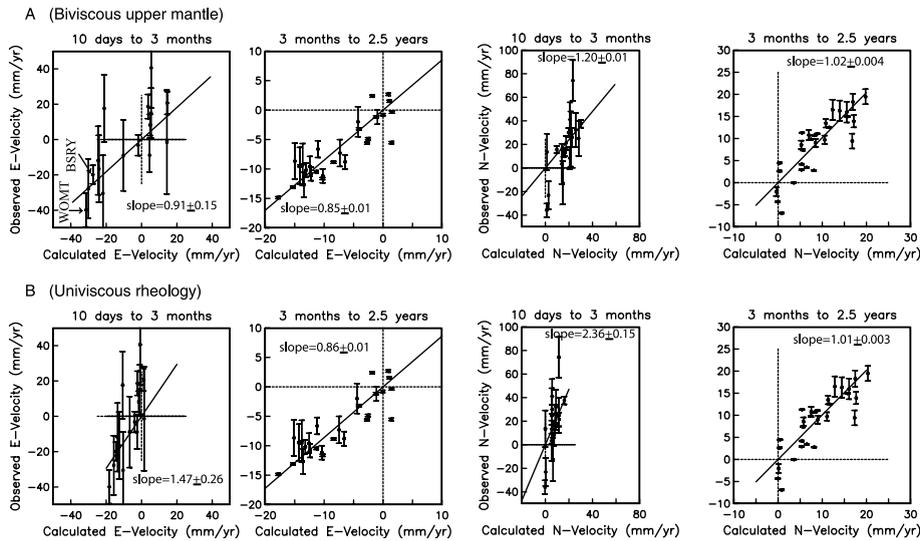


Fig. 7. Predicted horizontal velocities from (A) biviscous upper mantle rheology model (preferred model of Fig. 6c) and (B) univiscous (lower crust+upper mantle) model are compared with horizontal velocities derived from SCIGN continuous and USGS campaign time series for two postseismic time periods. Error bars represent one SD about the plotted point. Only those velocity estimates with SD less than 30 mm/yr are shown. In each plot, the best-fitting line constrained to pass through the origin is indicated together with the value of its slope and standard deviation. A slope of 1 would correspond to perfect agreement between model and observation. The slope much greater than 1 for the univiscous model during the 10 days–3 months period indicates model velocities that tend to underpredict observed velocities during the early postseismic period.

well, as shown in Fig. 8a for three different time periods, considering the errors generally present in vertical GPS measurements. The predicted spatial uplift pattern is shown in Fig. 10 where it is compared with compiled SCIGN uplift measurements for three postseismic epochs. The observed vertical velocity pattern is consistent with the predicted quadrant pattern for all time periods and further shows that the sign of the quadrant pattern is maintained with time. The class of biviscous lower crust models generally predicts a reversal in the sign of the quadrant pattern as time progresses (Fig. 8b), and the lack of such a reversal in the observations is the principal shortcoming of that model class. We note that the observed GPS uplift pattern is very similar to that revealed by InSAR for the first 9 months postseismic period [15], showing that vertical GPS and InSAR data carry similar implications for the rheology of this region.

An alternative postseismic deformation model would involve afterslip on discrete slip surfaces beneath those which ruptured in the Hector

Mine earthquake (Fig. 4d). We construct an afterslip model consisting of the downdip extensions (from 36–16 km depth) of representative coseismic rupture planes (the same geometry as in [15]) with a specified right-lateral slip within three different time intervals (1-m slip from 10 days to 3 months; 2-m slip from 10 days to 9 months; 1-m slip from 3 months to 2.5 years). The slip is chosen to yield approximate agreement with the observed horizontal velocity field, but our concern here is the vertical velocity field. The resulting postseismic uplift pattern (Fig. 8c) is anticorrelated with the observed postseismic uplift pattern for all time periods. Most of the sites are simply located in the wrong uplift quadrant, and a change in afterslip parameters is unlikely to remedy this situation, assuming that its slip must be in the right-lateral sense. In addition, the early-period (10 days to 3 months) horizontal velocity field generally exhibits large far-field postseismic velocity. For example, the East-velocity of BSRY and WOMT, both of which are  $> \sim 60$  km from the coseismic rupture, are large (Fig. 7a). In order to

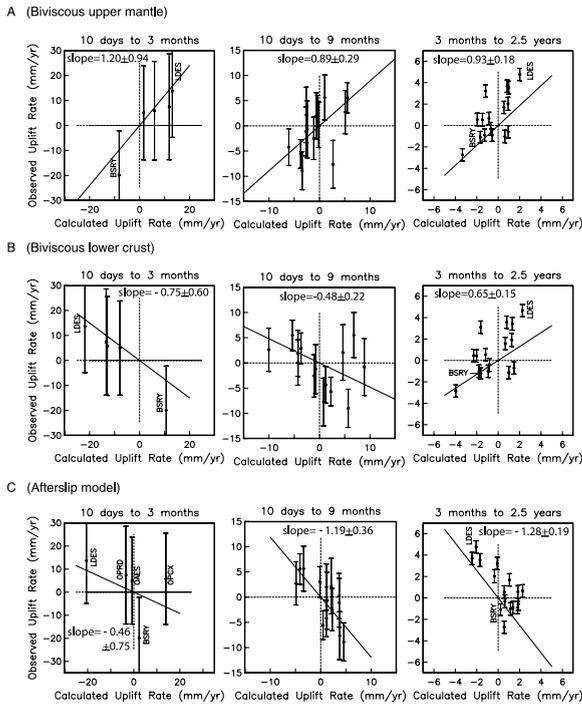


Fig. 8. Predicted uplift rates from (A) biviscous upper mantle rheology model (preferred model of Fig. 6c), (B) biviscous lower crust model defined in the text, and (c) afterslip model are compared with uplift rates derived from SCIGN continuous time series for three postseismic time periods. Error bars represent one SD about the plotted point. Only those velocity estimates with SD less than 30 mm/yr are shown. In each plot, the best-fitting line constrained to pass through the origin is indicated together with the value of its slope and SD. A slope of 1 would correspond to perfect agreement between model and observation.

fit these data simultaneously with smaller postseismic velocities of more nearby sites would require afterslip planes penetrating well into the mantle, which seems implausible.

For a strike-slip faulting event, poroelastic rebound of the upper crust, driven by dissipation of fluid pressure gradients created by the coseismic stress field, produces a postseismic uplift pattern opposite to the coseismic uplift pattern. This is qualitatively similar to that pattern predicted by the preferred biviscous mantle model, and significant poroelastic effects have been documented for the first  $\sim 5$  weeks following both the 1992 Landers earthquake [17] and the June 17, 2000, SISZ Iceland earthquake [39]. However, the spatial

scale of demonstrated poroelastic effects is  $\sim 3$  km, in accord with physical considerations based on the expected sharp decrease in permeability below 2–3 km depth [40]. This contrasts with the  $> \sim 20$ -km scale of postseismic uplift following the Hector Mine earthquake as displayed in Fig. 10. (The two most rapidly uplifting sites during the early postseismic periods are BSRY and LDES, both  $> 30$  km from the locus of coseismic slip.) Although the precise properties of poroelastic flow should be confirmed with realistic modeling, it is likely that its long wavelength signal in our data set is very small, especially with the exclusion of the first 10 days postseismic observations.

Our results suggest that the upper mantle beneath the Mojave Desert exhibits a transient rheology with two material decay constants of  $\tau_2 \sim 0.07$  and  $\tau_1 \sim 2$  years. If true, it raises the question of the mechanisms of relaxation responsible for the two very different relaxation regimes. Creep experiments on mineral samples at con-

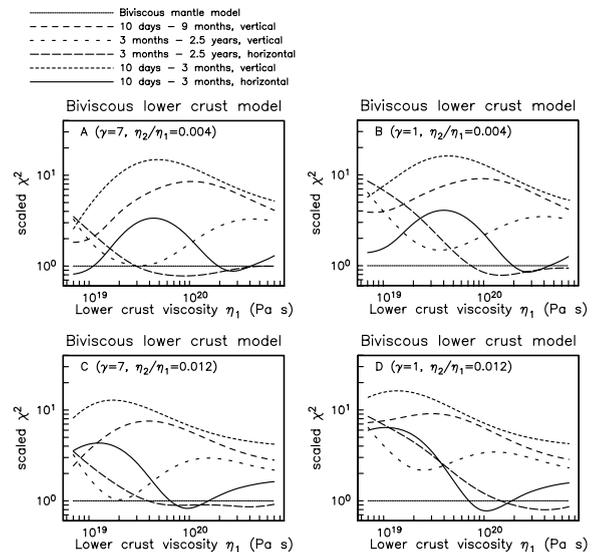


Fig. 9. Misfit of various velocity fields as a function of  $\eta_1$  for various slices of the biviscous lower crust model. Referring to Eq. 10, horizontal misfit is the sum  $\chi_1^2 + \chi_2^2$ , and vertical misfit is  $\chi_3^2$ . All models have fixed  $\mu' = 0.5 \times \mu_1$ . For each case, the misfit has been divided by the corresponding misfit achieved by the preferred biviscous mantle model. A value of unity thus corresponds to identical fit of a dataset by the two models.

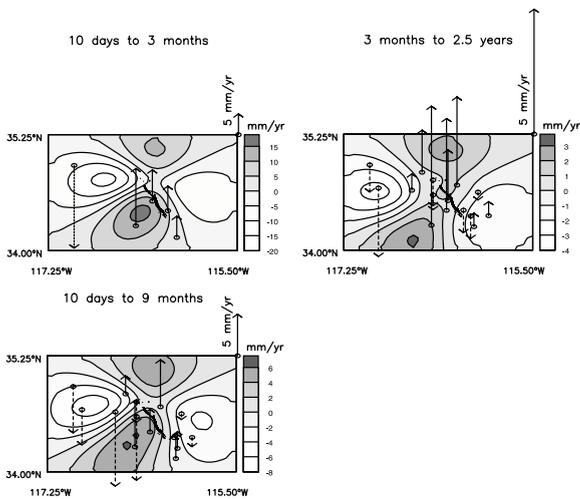


Fig. 10. Uplift of SCIGN sites with useful measurements (SD less than 30 mm/yr) during three postseismic periods, shown with continuous vertical bars (positive uplift) or dashed bars (negative uplift). These are compared with the corresponding predictions of the preferred biviscous model shown by the colored pattern. The area is as viewed from 45° from vertical.

stantly applied stress typically yield a transient phase of rapid strain rate followed by a phase of slower but essentially constant strain rate [20]. The later phase is associated with steady-state creep, for which many mechanisms are available [41–43]. In general, it is thought that the relative resistance to dislocation glide vs. dislocation climb [21] controls the nature of the transient stage. However, Karato [44] points out that ‘no systematic studies of transient creep have been made on olivine and olivine rich rocks’.

From the bound  $\gamma \geq \sim 7$  and the estimate of steady-state lower crust viscosity of  $\sim 3.2 \times 10^{19}$  Pa s, a relatively strong crust appears necessary to explain the Hector Mine postseismic GPS data. For comparison, an effective lower crust viscosity  $\sim 10^{20}$  Pa s has been inferred for the Lake Mead, Nevada region [45] and for the epicentral region of the 1959 Hebgen Lake earthquake [46].

The Kelvin element associated with transient viscosity  $\eta_2 = 1.6 \times 10^{17}$  Pa s inferred here is presumably one of several relaxation elements that compose an absorption band model of seismic wave attenuation. With  $\eta_1 \gg \eta_2$ , this value of  $\eta_2$  is comparable with the average-Earth value

$\eta_2 \sim O(10^{16})$  Pa s estimated to fit seismic  $Q$  of Earth’s lowest free oscillations with a single standard linear solid rheology [22]. The present modeling leaves open the question of whether the larger viscosity  $\eta_1 \sim 5 \times 10^{18}$  Pa s is the true long term viscosity of the upper mantle beneath the Mojave Desert, or whether it is itself another component of a generalized Burgers body rheology with a long term viscosity closer to  $\sim 10^{21}$  Pa s as suggested by mantle convection studies. This question is worth pursuing since it carries implications for the transition from anelastic to viscous behavior in Earth’s upper mantle. Karato [44] cites experimental evidence that the transient stage persists until a net strain of 1–2% is attained, which is thought to require 1000 s of years in postglacial rebound studies. If  $\eta_1$  is indeed the long term viscosity then it would imply that, on a local scale, the transition can take place at a much shorter timescale than on the continental-wide scale. It would also imply that the transition from anelastic to viscous deformation mechanisms has taken place within the time frame of the Hector Mine postseismic epoch. With a mantle strain rate of about  $10^{-5}$ /yr during the early post-Hector Mine period, clearly very little strain would accumulate in just a few weeks. I suggest that the bulk deformation behavior in the uppermost mantle may differ from the microscopic deformation behavior, possibly because of the presence of a sub-Moho macroscopic rock fabric of the type recently proposed by Fuchs et al. [47]. In any case, the present results appear to confirm Yuen and Peltier’s assertion [22] that the quasi-static deformation is partially ‘supported by the anelastic component of the complete rheology’.

## 6. Conclusions

The principal results of this study are the following.

(1) 3-D surface deformation measured by GPS in the epicentral region of the 1999 Hector Mine earthquake for the first 2.5 years after the earthquake are explained with a model of transient mantle rheology, specifically a linear biviscous rheology.

(2) A grid search performed on the three-component GPS time series for both the steady-state mantle viscosity  $\eta_1$  and transient viscosity  $\eta_2$  yield values of  $\eta_1 \sim 4.6 \times 10^{18}$  Pa s and  $\eta_2 = 1.6 \times 10^{17}$  Pa s. A Jeffreys solid (equal transient and steady-state shear moduli) appears most consistent with the observations.

(3) This model explains the observed pattern of rapid deformation during the first 0.2 year followed by an indefinite (and likely continuing) period of slower deformation, as well as the pattern of time-dependent postseismic uplift.

(4) Alternative models considered such as a transient rheology localized in the lower crust, a linear univiscous rheology, or deep afterslip fail to explain one or more of the essential features of the observations.

The plausibility of the transient rheology model does not rule out other possibilities to explain the postseismic deformation patterns. Another chief candidate mechanism is non-linear (stress and temperature-dependent) rheology of the lower crust and upper mantle [15]. This appears capable of explaining at least the horizontal postseismic GPS observations (Andy Freed, pers. commun.). All models considered up to the present are likely oversimplifications of the true rheology, which is likely laterally variable and characterized by several anelastic deformation mechanisms at all times. Regardless of the precise mechanisms, it appears that postseismic flow deep beneath the coseismic rupture and the involvement of processes occurring over several timescales, are robust properties of the postseismic epoch.

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